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# Predictive Global Optimization with Response Surface Modeling

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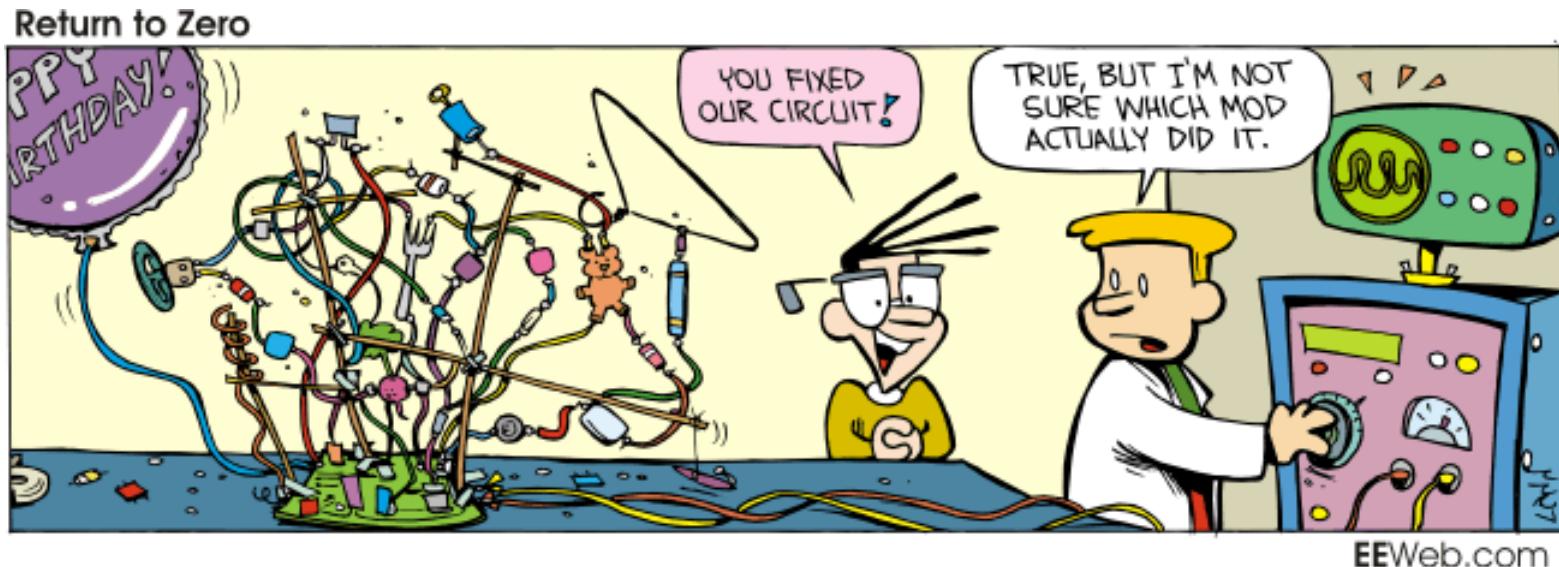
# Contents

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- ▶ Introduction and motivation
- ▶ Overall algorithm
- ▶ Details on algorithm components
- ▶ LC-VCO optimization example

# Schematic Level Circuit Design

- ▶ It's an optimization problem
  - ▶ Many design variables to consider
  - ▶ Also many performance constraints
  - ▶ Optimization needed for some performance(s)





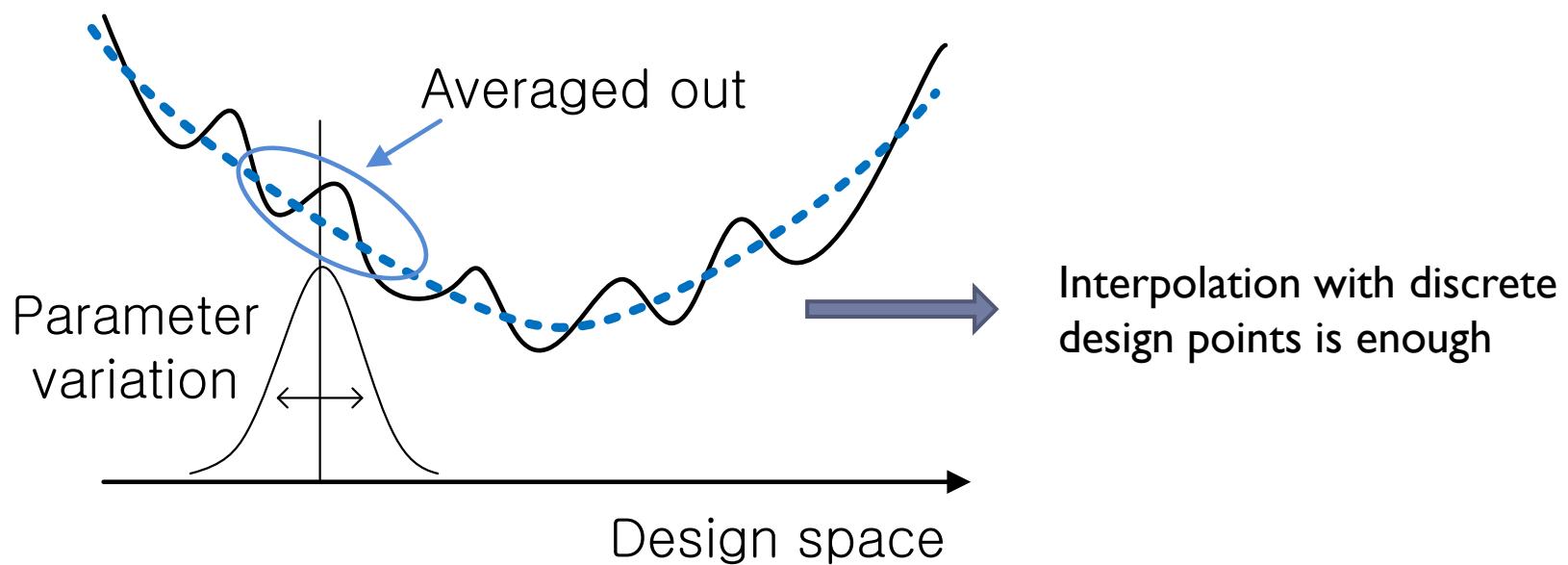
# Previous Approaches

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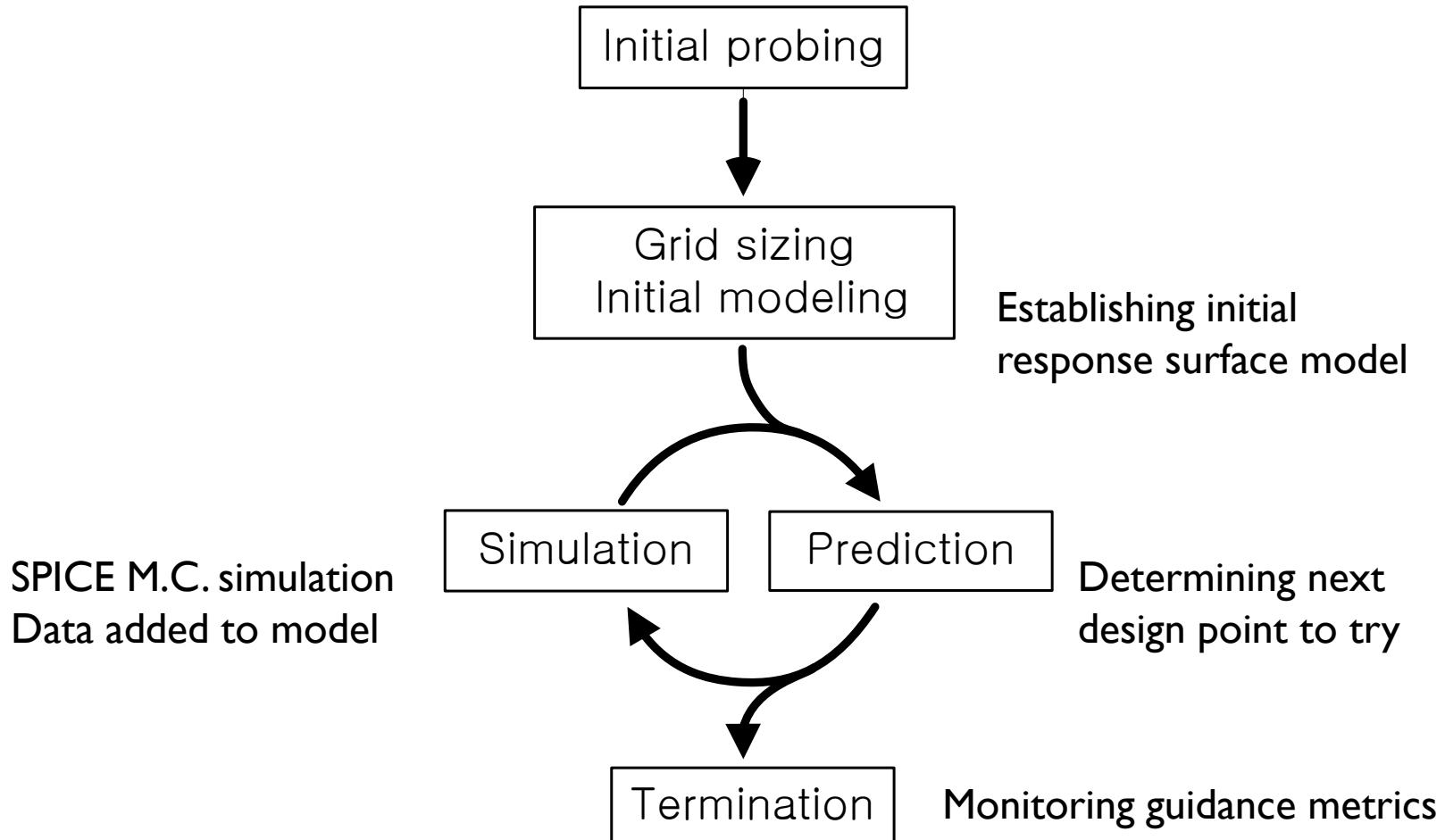
- ▶ Equation-based ones
  - ▶ convex optimization techniques
  - ▶ Fast execution
  - ▶ Accuracy and labor issues
  
- ▶ Simulation-based ones
  - ▶ Response surface modeling(RSM)
  - ▶ Genetic algorithms
  - ▶ SPICE level accuracy

# Motivation for RSM Method

- ▶ Circuit performance function is smooth
  - ▶ Design parameter variation averages out surface roughness
  - ▶ Correlation models the amount of smoothness



# Overall Algorithm





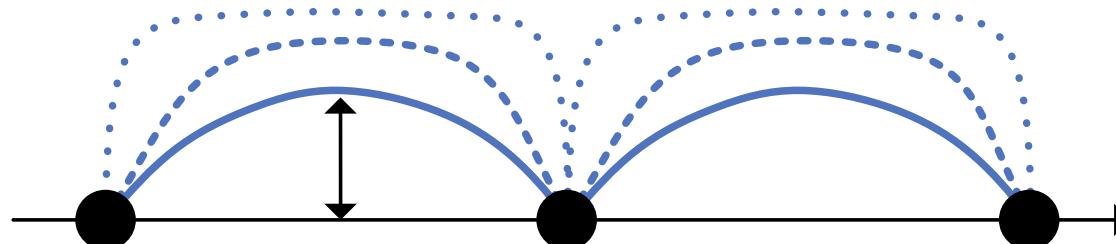
# Introducing Discrete Grid

- ▶ Using correlation of target performance function
  - ▶ Gaussian function for modeling correlation
    - ▶ e.g) Two points should have at least 0.5 correlation

$$\rho(\Delta_d) = e^{-\|\theta \Delta_d\|^2} \geq 0.5$$

$$\Delta_d \leq \frac{1}{\theta} \log 2$$

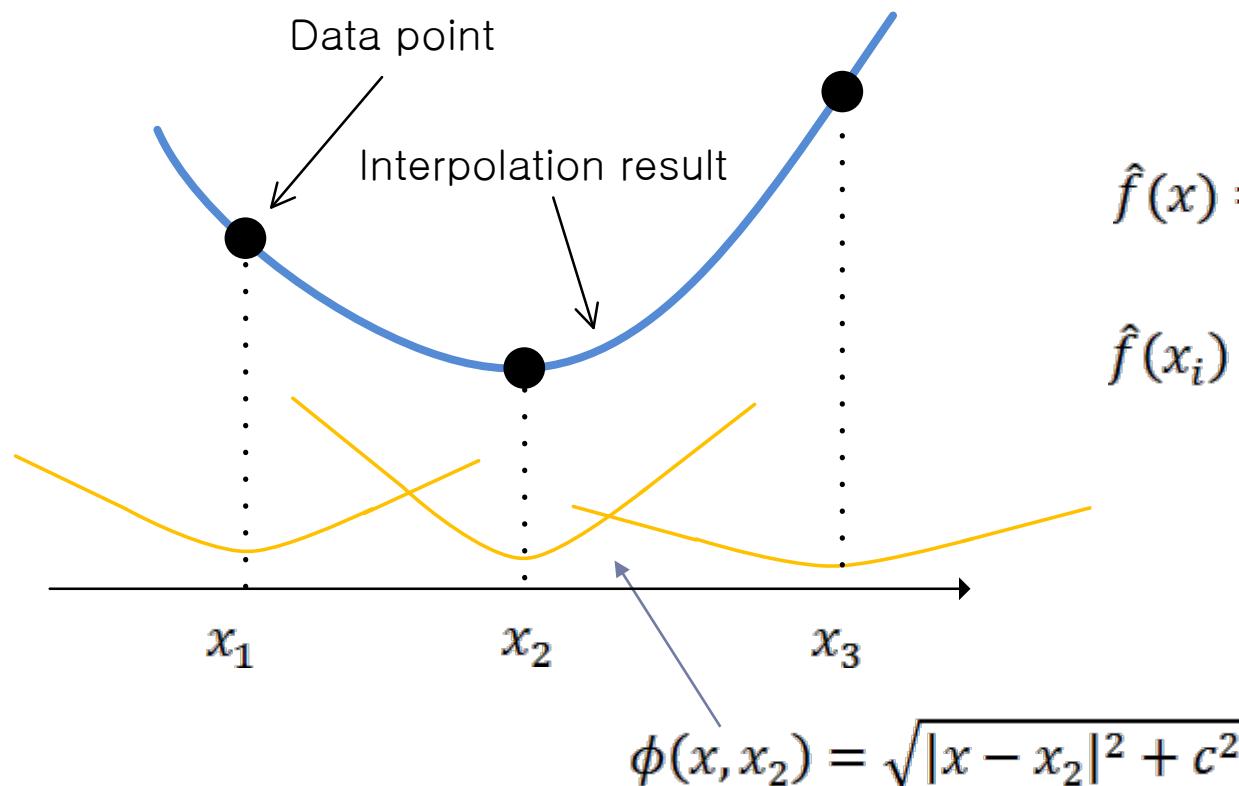
- ▶ Also related to interpolation uncertainty
  - ▶ The amount of uncertainty is determined by correlation





# Radial Basis Function Interpolation

- ▶ Linear combination of basis functions
- ▶ Multiquadric bases can do extrapolation

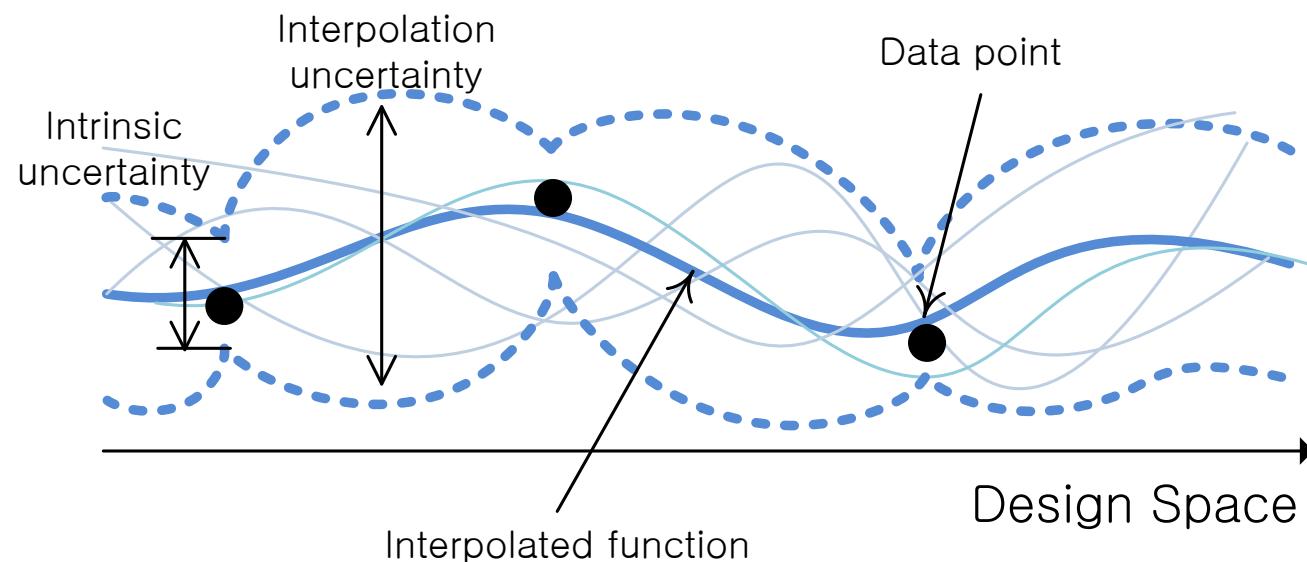


$$\hat{f}(x) = \sum_{i=1}^n \beta_i \phi(x, x_i)$$

$$\hat{f}(x_i) = f(x_i)$$

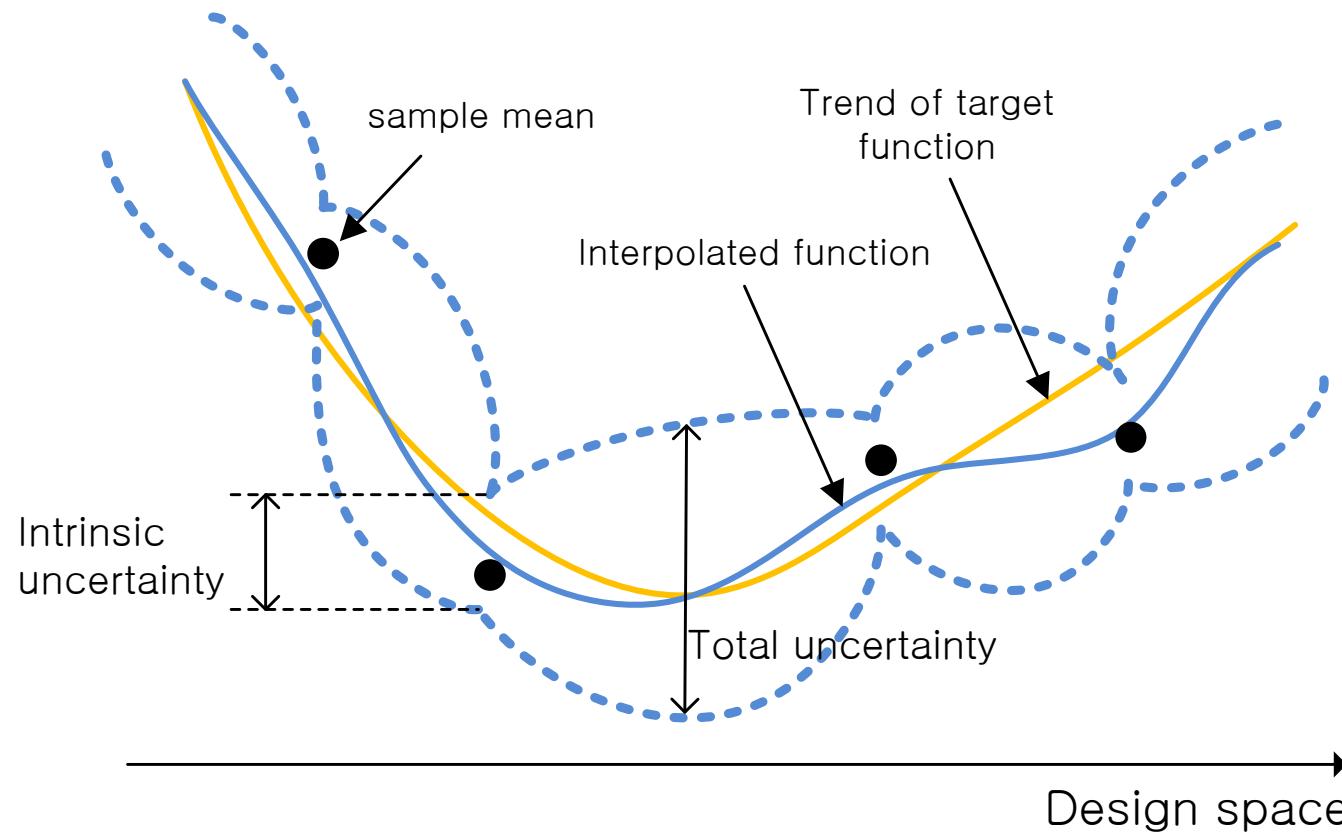
# Stochastic Kriging

- ▶ Estimate intermediate values using correlation
  - ▶ Also gives regularization for noisy data
- ▶ Measure for interpolation uncertainty
  - ▶ Intrinsic uncertainty and extrinsic uncertainty



# Desirable Regression Method

- ▶ Combining RBF interpolation and stochastic Kriging
- ▶ Model-order reduction applied on RBF term



# Model Equation

$$Y(\mathbf{d}) = \Phi^T(\mathbf{d})\boldsymbol{\beta} + Z(\mathbf{d}) + V(\mathbf{d})$$

↓

Mean surface      Gaussian Process

Noise

$$\Phi^T(\mathbf{d})\boldsymbol{\beta} = \Sigma_j (\phi(\mathbf{d}, \mathbf{d}_j)\boldsymbol{\beta}_j)$$

$$\phi(\mathbf{d}, \mathbf{d}') = \sqrt{\|\mathbf{d} - \mathbf{d}'\|^2 + c^2}$$

Rough global trend

$$Z(\mathbf{d}) \sim GP(0, \Sigma_Z)$$

$$\Sigma_Z(\mathbf{d}, \mathbf{d}') = \sigma_z^2 e^{-\|\theta^T(\mathbf{d}-\mathbf{d}')\|^2}$$

Local deviation

$$V(\mathbf{d}) \sim GP(0, \Sigma_V)$$

$$\Sigma_V(\mathbf{d}, \mathbf{d}') = \sigma_V^2(\mathbf{d}) \delta(\mathbf{d}, \mathbf{d}')$$

Noise in data

# Regression Equations

- ▶ Linear unbiased minimum mean-squared-error

Interpolated Value

$$\hat{Y}(d_{new}) = \Phi^T (\mathbf{d}_{new}) \hat{\beta} + \mathbf{r}^T(\mathbf{d}_{new}) \mathbf{K}^{-1} (\bar{Y}(\mathbf{D}) - \Phi \hat{\beta})$$

Extrapolative trend      Compensation

Deviation from trend

Total uncertainty

$$MSE(d_{new}) = \sigma_V^2(d_{new}) + \sigma_Z^2 \left( 1 - [\Phi^T \quad \mathbf{r}^T] \begin{bmatrix} 0 & \Phi^T \\ \Phi & \mathbf{K} \end{bmatrix}^{-1} [\Phi \quad \mathbf{r}] \right)$$

Intrinsic variation      Interpolation uncertainty

# Guidance Metrics for Optimization

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- ▶ Determining next point to simulation
  - ▶ Approximate performance distribution on unvisited design point

$$\begin{aligned}\hat{m}(d_{\text{new}}) &\sim N(m_0, \epsilon_m^2) \\ \hat{s}(d_{\text{new}}) &\sim N(s_0, \epsilon_s^2)\end{aligned}\quad \Rightarrow f(d_{\text{new}}) \sim N(\hat{m}(d_{\text{new}}), \hat{s}(d_{\text{new}})^2)$$

- ▶ For constraints, probability for feasibility

$$\text{Prob}(f(d_{\text{new}}) > \theta)$$

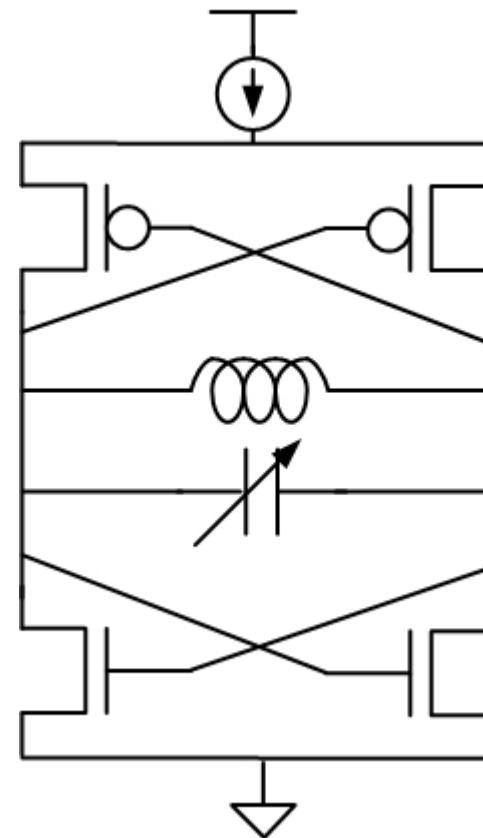
- ▶ For objective, expected improvement

$$E[\max(0, f(d_{\text{new}}) - f^*)]$$



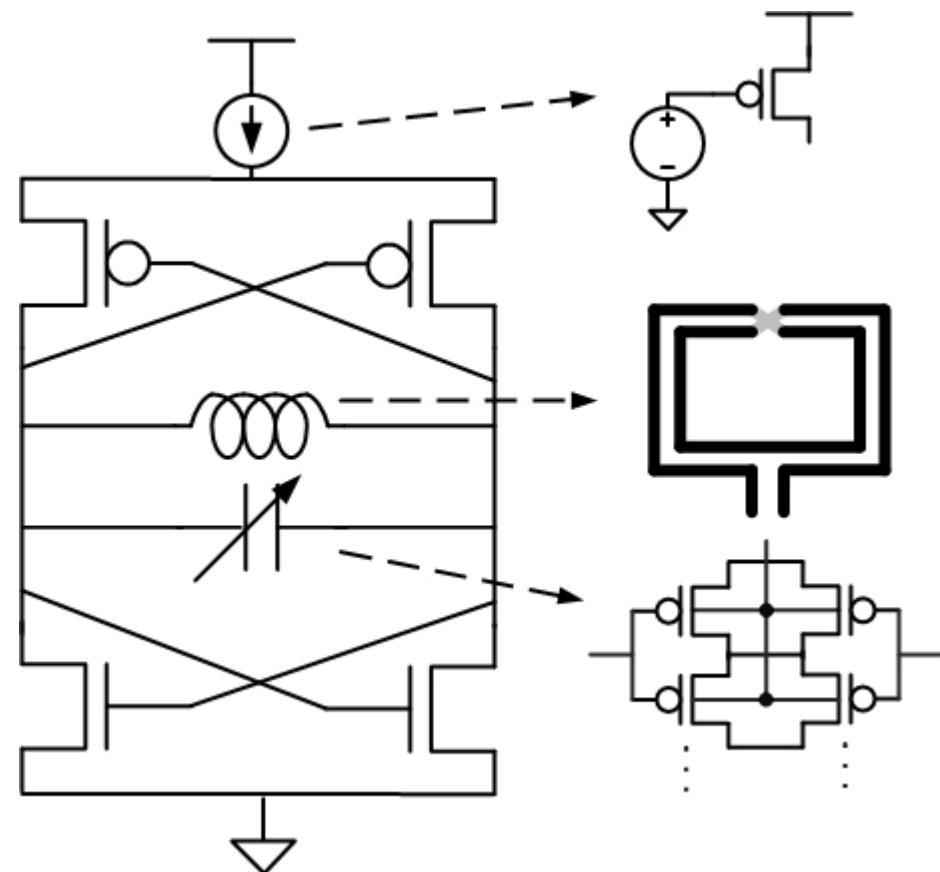
# LCVCO Optimization

- ▶ Frequency Range
    - ▶ Min frequency < 6GHz
    - ▶ Max frequency > 7GHz
  - ▶ Startup condition
    - ▶  $\frac{g_m^{-1}}{R_{tank}} > 5$
  - ▶ Phase noise
    - ▶ Minimize @ 10MHz offset
- \* Fixed power consumption

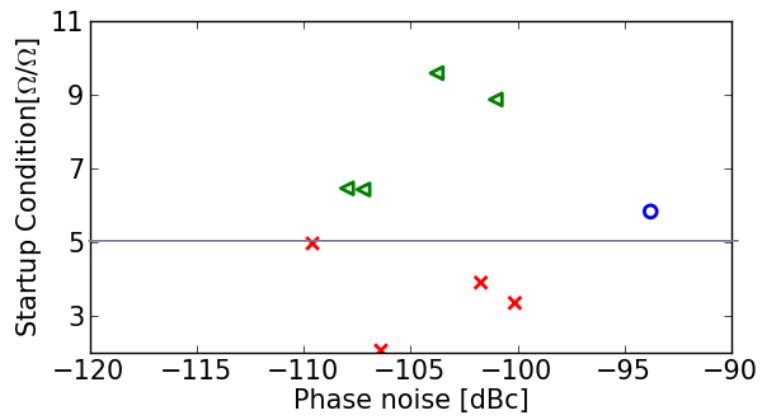
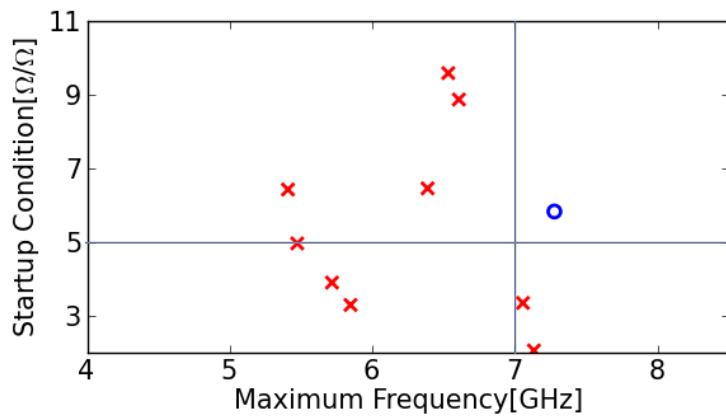
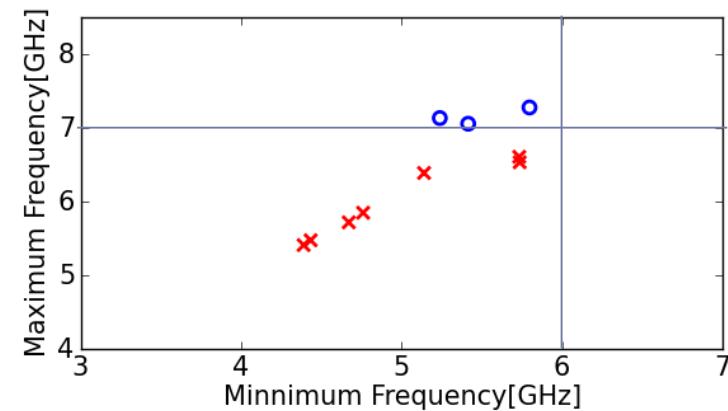
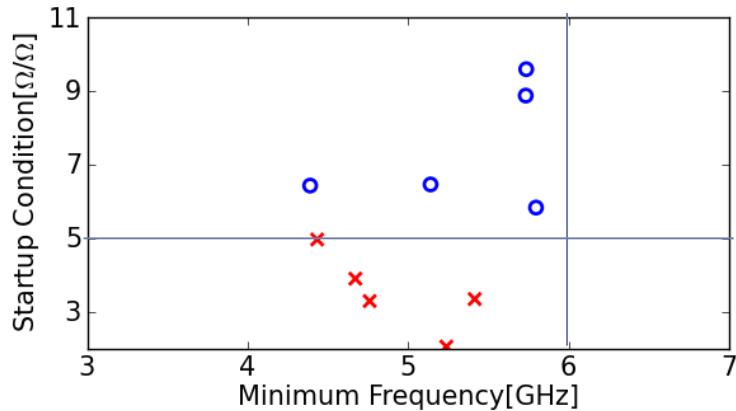


# LCVCO Optimization

- ▶ Design variables
  - ▶ Gm cells
    - ▶ PMOS widths
    - ▶ NMOS widths
  - ▶ MOS Varactor
    - ▶ Number of MOS's
  - ▶ Spiral inductor
    - ▶ Radius
    - ▶ Track width

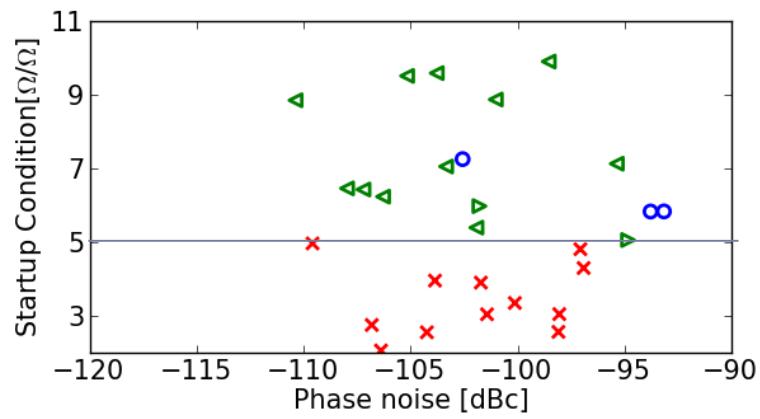
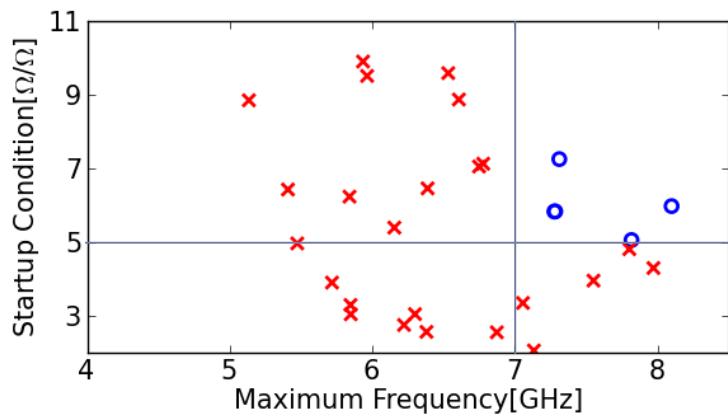
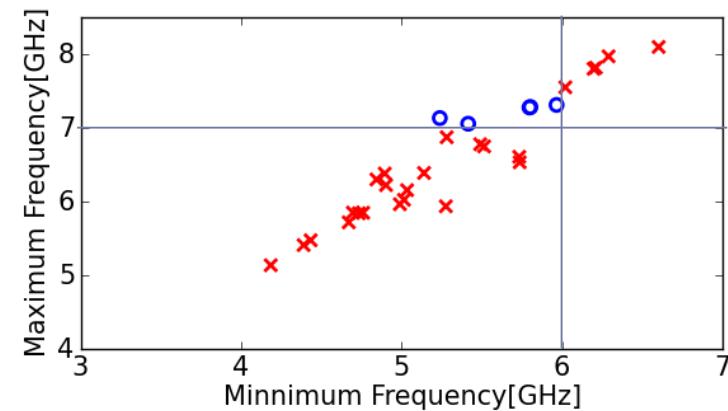
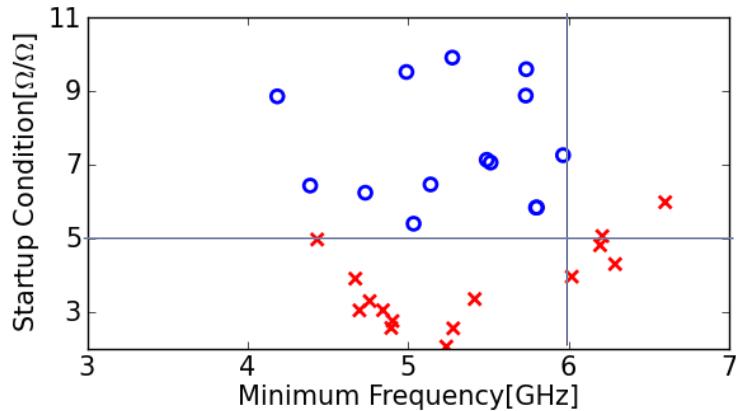


# Performance Space Visualization



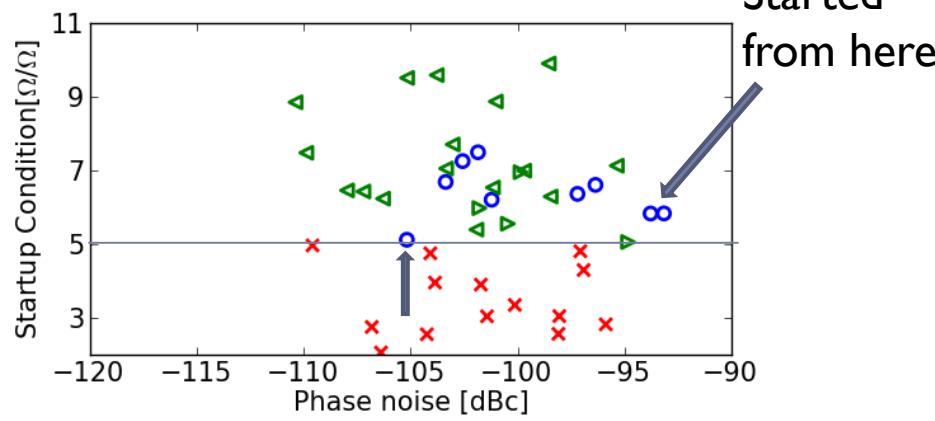
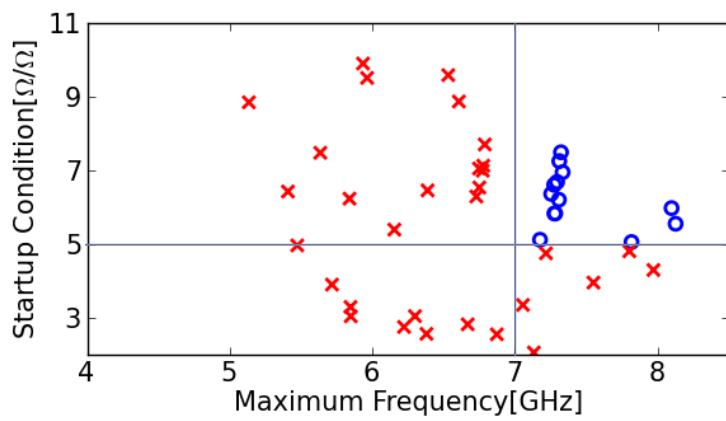
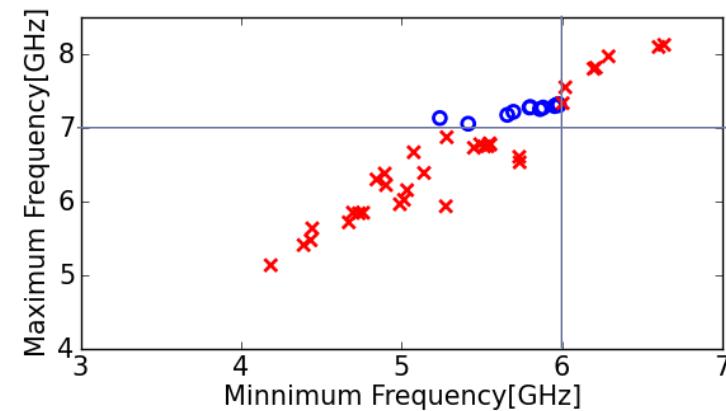
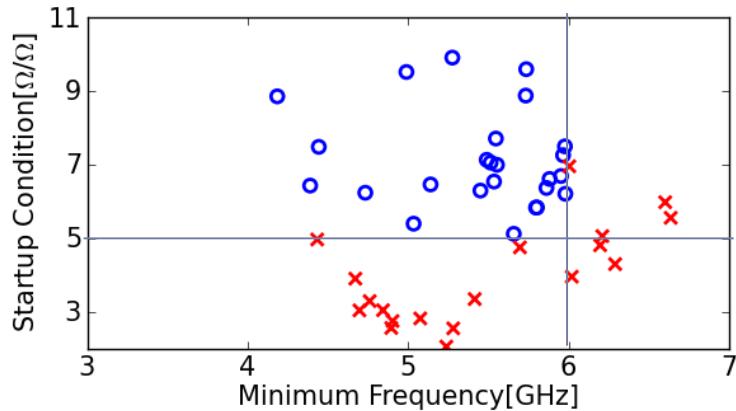
After initial random probing

# Performance Space Visualization



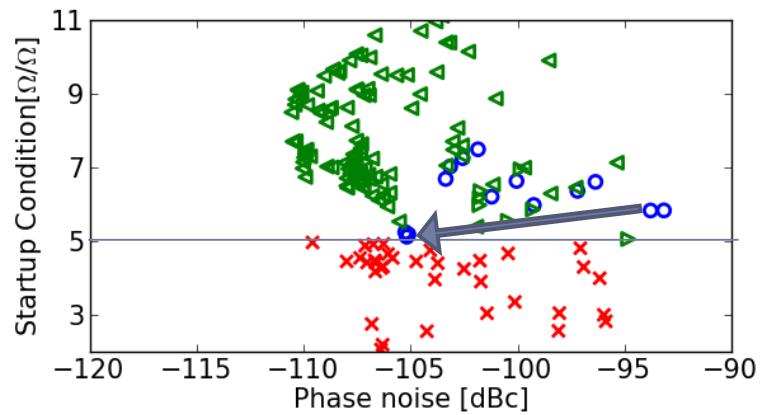
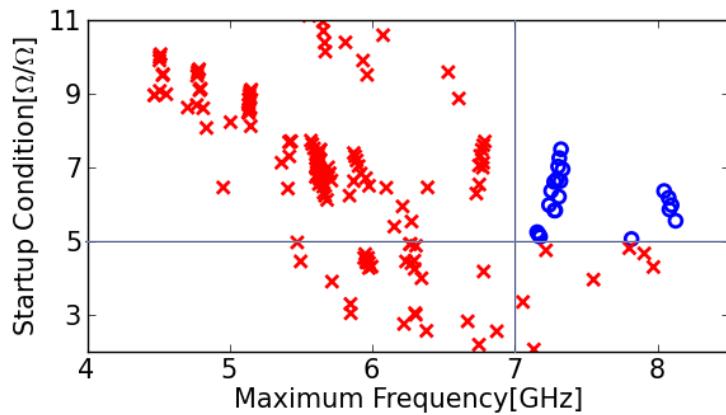
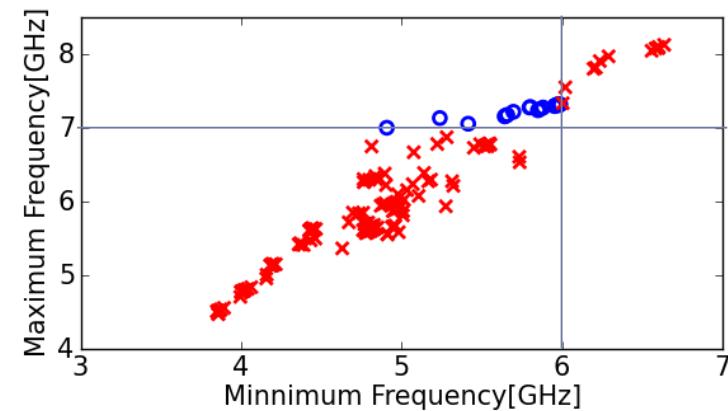
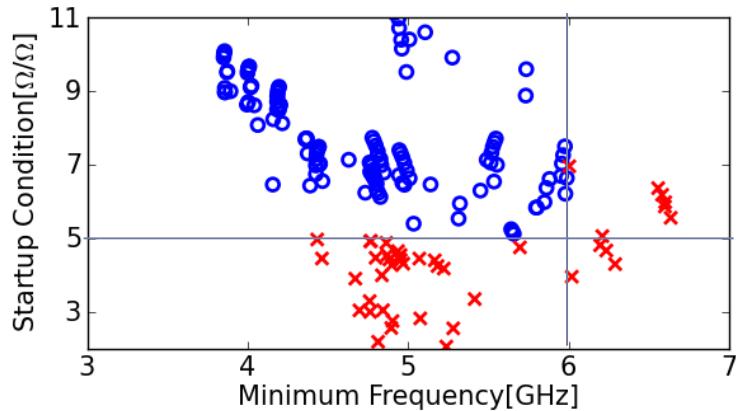
Model refinement for constraint metrics

# Performance Space Visualization



Detection of optimum

# Performance Space Visualization



Visiting additional data points with  
low probability for feasibility

# Summary & Future work

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- ▶ Global optimization with discretized design space
  - ▶ RBF and Stochastic Kriging are combined for modeling
  - ▶ Design space discretization based on correlation
- ▶ LCVCO circuit is tested for optimization
  - ▶ Early detection of optimum out of total iteration
- ▶ Extend to verification problems

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- ▶ Jones, Donald R., Matthias Schonlau, and William J. Welch. "Efficient global optimization of expensive black-box functions." *Journal of Global optimization* 13.4 (1998): 455-492.
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# THANK YOU